## Modeling and Specification

in OTS/CafeOBJ

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## Topics

- What is QLOCK?
- Modeling and Description of QLOCK in OTS
- Formal specification of QLOCK in CafeOBJ
- Formal specification of mutual exclusion

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Modeling, Specifying, and Verifying (MSV)
in CafeOBJ
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1. By understanding a problem to be modeled/specified, determine several sorts of objects (entities, data, agents, states) and operations (functions, actions, events) over them for describing the problem
2. Define the meanings/functions of the operations by declaring equations over expressions/terms composed of the operations
3. Write proof scores for properties to be verified

Understand problem and construct model


Assume that many agents (or processes) are competing for a common equipment, but at any moment of time only one agent can use the equipment. That is, the agents are mutually excluded in using the equipment. A protocol (mechanism or algorithm) which can achieve the mutual exclusion is called "mutual exclusion protocol".

## QLOCK (locking with queue):

a mutual exclusion protocol

Each agent i is executing: $\quad \square$ : atomic action


## QLOCK: basic assumptions/characteristics

- There is only one queue and all agents/processes share the queue.
- Any basic action on the queue is inseparable (or atomic). That is, when any action is executed on the queue, no other action can be executed until the current action is finished.
- There may be unbounded number of agents.
- In the initial state, every agents are in the remainder section (or at the label rm), and the queue is empty.

The property to be shown is that at most one agent is in the critical section (or at the label cs) at any moment.

Global (or macro) view of QLOCK



## Signature for QLOCKwithOTS

- Sys is the sort for representing the state space of the system.
- Pid is the sort for the set of agent/process names.
- Label is the sort for the set of labels; i.e. $\{\mathrm{rm}, \mathrm{wt}, \mathrm{cs}\}$.
- Queue is the sort for the queues of Pid
- pc (program counter) is an observer returning a label where each agent resides.
- queue is an observer returning the current value of the waiting queue of Pid.
- want is an action for agent $i$ of putting its namelid into the queue.
- try is an action for agent $i$ of checking whether its namelid is at the top of the queue.
- exit is an action for agent $i$ of removing/getting its namelid from the top of the queue.


## CafeOBJ signature for QLOCKwithOTS

| -- state space of the system <br> *[Sys]* |  |
| :--- | :--- |
| -- visible sorts for observation |  |
| [Queue Pid Label] |  |$\quad$ visible sort declaration

## Module LABEL specifying

(via tight denotation/semantics) "labels"

```
mod! LABEL {
    [Label]
    ops rm wt cs : -> Label
    pred (_=_) : Label Label {comm}
    var L : Label
    eq (L = L) = true.
    eq (rm = wt) = false
    eq (rm = cs) = false
    eq (wt = cs) = false .
}
```

Predicate (_ = _) defines identity relation among rm, wt, and cs.

## Module PID specifying (via loose denotation)

 "agent/process names/identifiers"mod* PID \{
[Pid < PidErr]
op none : -> PidErr
pred (_=_) : PidErr PidErr \{comm\}
var I : Pid .
eq (I = I) = true .
eq (none $=\mathrm{I}$ ) = false
-- (none $=$ none) is not defined intentionally
\}

- The constant none of the sort PidErr is intended to indicate the result of getting top of the empty queue.
- Any element in the sort Pid is defined not equal to none, that is, return false for predicate ( $=_{-}$).
- Notice that (none $=$ none) does not reduced to true or false.


## Module QUEUE specifying "queue"

```
mod* TRIVerr {
    [Elt < EltErr]
    op none : -> EltErr
}
mod! QUEUE(D :: TRIVerr) {
    [Queue]
-- constructors
    op empty : -> Queue {constr}
    op _r_ : Queue Elt.D -> Queue {constr l-assoc}
-- operators
    op put : Elt.D Queue -> Queue
    op get : Queue -> Queue
    op top : Queue -> EltErr.D
    op empty? : Queue -> Bool
```


## Module QUEUE specifying "queue" (2)

-- an parameterized module

```
-- CafeOBJ variables
    var Q : Queue
    vars X Y : Elt.D
-- equations
    eq put(X,empty) = empty,X .
    eq put(X,(Q,Y)) = put(X,Q),Y .
    -- get(empty) is not defined intentionally
    eq get((Q,X)) = Q .
    eq top(empty) = (none):EltErr.D .
    eq top((Q,X)) = X .
    eq empty?(empty) = true .
    eq empty?((Q,X)) = false .
}
```

Each agent $i$ is executing: $\square$ : atomic action


## Module QLOCK specifying "QLOCK" (1-1)

```
view TRIVerr2PID from TRIVerr to PID {
    sort Elt -> Pid,
    sort EltErr -> PidErr,
    op (none):EltErr -> (none):PidErr }
```

mod* QLOCK \{
pr(LABEL)
pr(QUEUE(D <= TRIVerr2PID))
*[Sys]*
-- any initial state
op init : -> Sys
-- observations
bop pc : Sys Pid -> Label
bop queue : Sys -> Queue
-- actions
bop want : Sys Pid -> Sys
bop try : Sys Pid -> Sys
bop exit : Sys Pid -> Sys
-- for any initial state
eq pc(init,I:Pid) = rm .
eq queue(init) = empty

## Module QLOCK specifying "QLOCK" (1-2)

```
mod* QLOCK {
    pr(LABEL)
    pr(QUEUE(PID{sort Elt -> Pid,
                sort EltErr -> PidErr
                op (none):EltErr -> none):PidErr}))
    *[Sys]*
-- any initial state
    op init : -> Sys
-- observations
    bop pc : Sys Pid -> Label
    bop queue : Sys -> Queue
-- actions
    bop want : Sys Pid -> Sys
    bop try : Sys Pid -> Sys
    bop exit : Sys Pid -> Sys
-- for any initial state
    eq pc(init,I:Pid) = rm
    eq queue(init) = empty .
```

```
Module QLOCK specifying "QLOCK" (2)
```

var S : Sys . vars I J : Pid

```
var S : Sys . vars I J : Pid
-- for want
-- for want
op c-want : Sys Pid -> Bool {strat: (0 1 2)}
op c-want : Sys Pid -> Bool {strat: (0 1 2)}
eq c-want(S,I) = (pc(S,I) = rm) .
eq c-want(S,I) = (pc(S,I) = rm) .
ceq pc(want(S,I),J)
ceq pc(want(S,I),J)
    = (if I = J then wt else pc(S,J) fi)
    = (if I = J then wt else pc(S,J) fi)
    if c-want(S,I).
    if c-want(S,I).
ceq queue(want(S,I)) = put(I,queue(S))
ceq queue(want(S,I)) = put(I,queue(S))
    if c-want(S,I) .
    if c-want(S,I) .
ceq want(S,I) = S
ceq want(S,I) = S
    if not c-want(S,I).
```

    if not c-want(S,I).
    ```

\section*{Module QLOCK specifying "QLOCK"}
```

-- for try
op c-try : Sys Pid -> Bool \{strat: (0 1 2 1 )\}
eq $c-\operatorname{try}(S, I)=(p c(S, I)=w t$ and top(queue(S)) $=I)$.
ceq pc(try(S,I),J)
$=$ (if $I=J$ then cs else $p c(S, J)$ fi) if c-try $(S, I)$.
eq queue(try(S,I)) = queue(S).
ceq $\operatorname{try}(S, I) \quad=S \quad$ if not $c-t r y(S, I)$.
-- for exit
op c-exit : Sys Pid -> Bool \{strat: ( 0 1 2) \}
eq c-exit $(S, I)=(p c(S, I)=c s)$
ceq pc(exit(S,I), J)
$=$ (if $I=\mathbf{J}$ then $r m$ else $p c(S, J)$ fi) if c-exit( $S, I)$.
ceq queue(exit $(S, I))=\operatorname{get}(q u e u e(S))$ if cexit(S,I).
ceq exit(S,I) $\quad=S \quad$ if not c-exit(S,I)
\}

```

\section*{(_ =*= _) is congruent for OTS}

The binary relation (S1:Sys =*= S2:Sys) is defined to be true iff S 1 and S 2 have the same observation values.

OTS style of defining the possible changes of the values of obervations is characterized by the equations of the form: \(o\left(a(s, d), d^{\prime}\right)=\ldots o_{1}\left(s, d_{1}\right) \ldots o_{2}\left(s, d_{2}\right) \ldots o_{n}\left(s, d_{n}\right) \ldots\) for appropriate data values of \(d, d^{\prime}, d_{1}, d_{2}, \ldots, d_{n}\).

It can be shown that OTS style guarantees that (_ =*= _) is congruent with respect to all actions.

\section*{\(\mathrm{R}_{\text {QLock }}\) (set of reachable states) of OTS OLOCK (OTS defined by the module QLOCK)}

\section*{Signature determining \(\mathbf{R}_{\text {QLOCK }}\)}
-- any initial state
op init : -> Sys
- actions
bop want : Sys Pid -> Sys
bop try : Sys Pid -> Sys
bop exit : Sys Pid -> Sys

Recursive definition of \(\mathrm{R}_{\text {QLock }}\)
\(R_{\text {QLock }}=\{\) init \(\} \cup\)
\{want(s,i)|sGR \(\left.\mathrm{R}_{\text {Lock }}, i \in \operatorname{Pid}\right\}\)
\(U\)
\(\left\{\operatorname{try}(s, i) \mid s \in R_{\text {QLock }}, i \in \operatorname{Pid}\right\} \cup\)
\(\left\{\operatorname{exit}(s, i) \mid s \in \mathrm{R}_{\mathrm{QLOCK}}, i \in \operatorname{Pid}\right\}\)

\section*{Mutual exclusion property as an invariant}
mod INV1 \{
    pr(QLOCK)
-- declare a predicate to verify to be an invariant
    pred inv1 : Sys Pid Pid
-- CafeOBJ variables
    var S : Sys.
    vars I J : Pid.
    - define inv1 to be the mutual exclusion property
    eq inv1(S,I,J)
        \(=(((\mathrm{pc}(\mathrm{S}, \mathrm{I})=\mathrm{cs})\) and \((\mathrm{pc}(\mathrm{S}, \mathrm{J})=\mathrm{cs}))\) implies \(\mathrm{I}=\mathrm{J})\)
\}
    Formulation of proof goal for mutual exclusion property
    INV1 |= \(\forall s \in R_{\text {QLOCK }} \forall i, j \in \operatorname{Pid.inv1(s,i,j)}\)

Induction scheme induced by the structure of \(\mathrm{R}_{\text {QLOCK }}\)
\[
m x(s)=_{\text {def }} \forall i, j \in \operatorname{Pid} . \operatorname{inv1}(s, i, j)
\]
```

{ INV1 |= mx(init),
INV1U{mx(s)=true} |= \forallk . mx(want(s,k)),
INV1U{mx(s)=true} |= \forallk . mx(try(s,k)),
INV1U{mx(s)=true} |= \forallk . mx(exit (s,k)) }
implies

```

```

