

I618 Advanced Computer Science II (Part II)

12/21 11:00-12:30
1/ 7 15:10-16:40
1/ 9 9:20-10:50
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Introduction

- Representative approaches to (\mathcal{NP} -)hard problems are...
 - approximation algorithms
 - exact algorithms with exponential time
 - restrictions on inputs
 - some special graph classes

Introduction

A graph $G=(V,E)$ is an *intersection graph* over set V of objects iff $\{v,u\}$ is in E if and only if corresponding objects are overlapping.

- We will mainly discuss about
 - Chordal graphs and interval graphs
 - typical intersection graphs
 - many applications
 - matrix manipulation, bioinformatics, scheduling, ...
 - many useful graph theoretic properties
 - typical subclasses of Perfect Graphs

1960 [Berge]: Strong Perfect Graph **Conjecture**



2002 [Chudnovsky, Cojuncjols, Liu, Seymour, and Vuskovic]:
Strong Perfect Graph **Theorem**

Introduction

- We will mainly discuss about
 - Chordal graphs and interval graphs
 - typical intersection graphs
 - many applications
 - Matrix manipulation, bioinformatics, scheduling, ...
 - many useful graph theoretic properties
 - typical subclasses of Perfect Graphs
 - many \mathcal{NP} -hard problems become *tractable* on those graph classes
 - △ several problems are *still hard* on those graph classes

Interval Graphs

[Today's Goal]

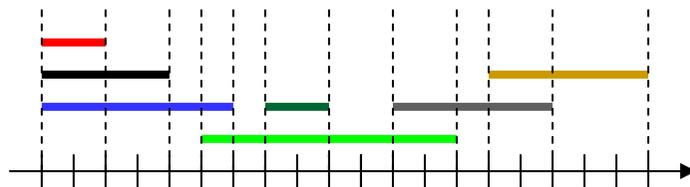
For any given interval graph, its maximum clique can be found in linear time.

(C.f., the maximum clique problem is \mathcal{NP} -complete in general.)

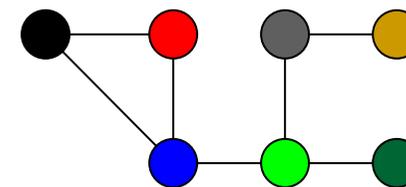
■ Simplest intersection graphs

- Since 195?- (Hajos (Graph theorist) & Benzer (Biologist))

[Definition 1] A graph $G=(V,E)$ with $V=\{v_1,v_2,\dots,v_n\}$ is an *interval graph* if and only if there is a set \mathcal{I} of intervals $\{I_1, I_2, \dots, I_n\}$ such that $\{v_i, v_j\} \in E$ if and only if I_i intersects I_j . We call \mathcal{I} an *interval representation* of G .



interval representation



corresponding graph

Interval Graphs

[Description]

open interval... 

closed interval... 

mixed interval... 

- Interval representations of an interval graph
 - is an interval open or closed?
 - *open*... e.g., $(1,5)$ does *not* contain the value 5.
 - *closed*... e.g., $[2,8]$ contains the value 8.
 - Let \mathcal{C}_o , \mathcal{C}_c , \mathcal{C}_m be the classes of interval graphs that consist of *open* intervals, *closed* intervals, and *mixed*, respectively.

[Theorem 1] $\mathcal{C}_o = \mathcal{C}_c = \mathcal{C}_m$

(Proof) We show that ① $\mathcal{C}_o \subseteq \mathcal{C}_c$ ② $\mathcal{C}_c \subseteq \mathcal{C}_m$ and ③ $\mathcal{C}_m \subseteq \mathcal{C}_o$.

- ① Let \mathcal{I}_o be an interval representation of an interval graph G such that \mathcal{I}_o only contains open intervals. Then, we construct \mathcal{I}_c that is an interval representation of G and \mathcal{I}_c only contains closed intervals as follows.

[Notation]

For an interval I , we denote the left endpoint by $L(I)$, and the right endpoint by $R(I)$.

Interval Graphs

[Description]

open interval... 

closed interval... 

mixed interval... 

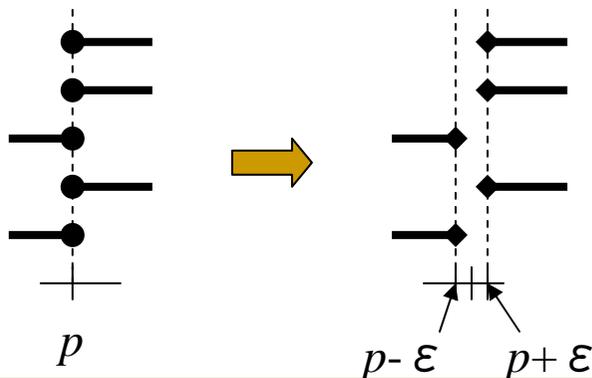
■ Interval representations of an interval graph

[Theorem 1] $\mathcal{C}_o = \mathcal{C}_c = \mathcal{C}_m$

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- ① Let \mathcal{I}_o be an interval representation of an interval graph G such that \mathcal{I}_o only contains open intervals. Then, we construct \mathcal{I}_c that is an interval representation of G and \mathcal{I}_c only contains closed intervals as follows.

For each point p that is an endpoint of at least one interval, we modify the intervals as follows for sufficiently small ε :

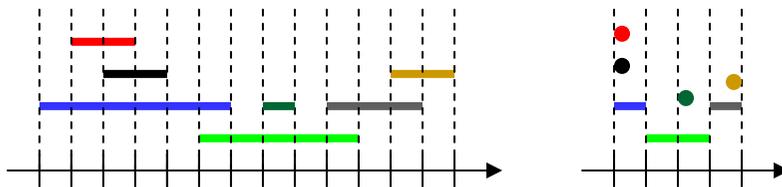


Repeating this process, we can obtain a closed interval representation \mathcal{I}_c of G .

② is trivial, and ③ is similar to ①. Hence we have the theorem. \square

Interval Graphs

- Interval representations of an interval graph
 - Hereafter,
 - By Theorem 1, we assume that all intervals are closed.
 - All endpoints are integers, and leftmost endpoint is 0.
 - We have two natural interval models;
 1. Each endpoint takes distinct value in $[0..2n-1]$ with n vertices (conversely, each integer in $[0..2n-1]$ corresponds to exactly one endpoint).
 2. We admit $L(I)=R(I)$, that is, the length of an interval can be 0, and intervals have *no redundancy*.



We call the second type “*compact representation*”.

Interval Graphs

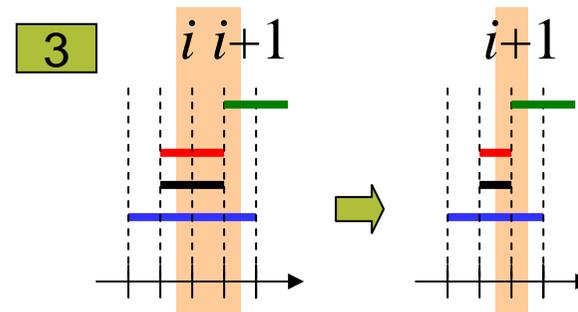
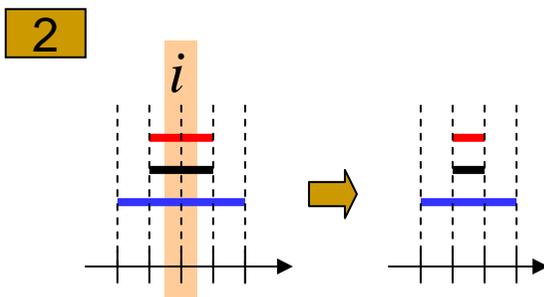
[Notation]

For a point p , let $N[p]$ denote the set of intervals that contain p .

- *Compact* interval representations of an interval graph

[Definition 2] An interval representation \mathcal{I} is called *compact* if it satisfies the following conditions;

1. (all endpoints are integers and the leftmost endpoint is 0,)
2. each integer i corresponds to at least one endpoint with $0 \leq i \leq k$ for some positive integer k , and
3. for each integer i with $0 \leq i < k$, we have $N[i] \not\subset N[i+1]$ and $N[i+1] \not\subset N[i]$.



Interval Graphs

[Notation]

For an interval representation \mathcal{I} , we denote by $L(\mathcal{I}) := \min_{I \in \mathcal{I}} L(I)$ and by $R(\mathcal{I}) := \max_{I \in \mathcal{I}} R(I)$

- *Compact* interval representations of an interval graph

[Theorem 2] Let \mathcal{I} be a *compact* interval representation of a *connected* interval graph $G=(V,E)$ of n vertices with $n \geq 2$. Then $L(\mathcal{I})=0$ and $R(\mathcal{I})=k$ for some integer k . Then, $k \leq n-2$.

[Lemma 1] Let \mathcal{I} be a *compact* interval representation of a *connected* interval graph $G=(V,E)$. Then there exists an interval $I \in \mathcal{I}$ such that $[L(I), R(I)] = [0, 0]$.

(Proof) of Lemma 1. We have two cases;

1. $[L(\mathcal{I}), R(\mathcal{I})] = [0, 0]$ (C.f. G is a complete graph): Trivial.
2. $R(\mathcal{I}) > 0$: If there are no such intervals, we have $N[1] = N[2]$ or $N[1] \subset N[2]$. Both cases contradict to the assumption that \mathcal{I} is a *compact* interval representation. \square

Interval Graphs

[Notation]

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- *Compact* interval representations of an interval graph

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(Proof) of Theorem 2. We prove by induction for k .

1. $k=0$: The graph G is a complete graph, and easy to see that $k \leq n-2$.
2. $k>0$: By Lemma 1, there are x intervals I with $R[I]=L[I]=0$ with $x>0$. We then remove them from \mathcal{I} and obtain \mathcal{I}' with $n-x$ intervals. Then, by the inductive hypothesis, we have $k-1 \leq n-x-2$. Hence we have $k \leq n-2$ since $x>0$. \square

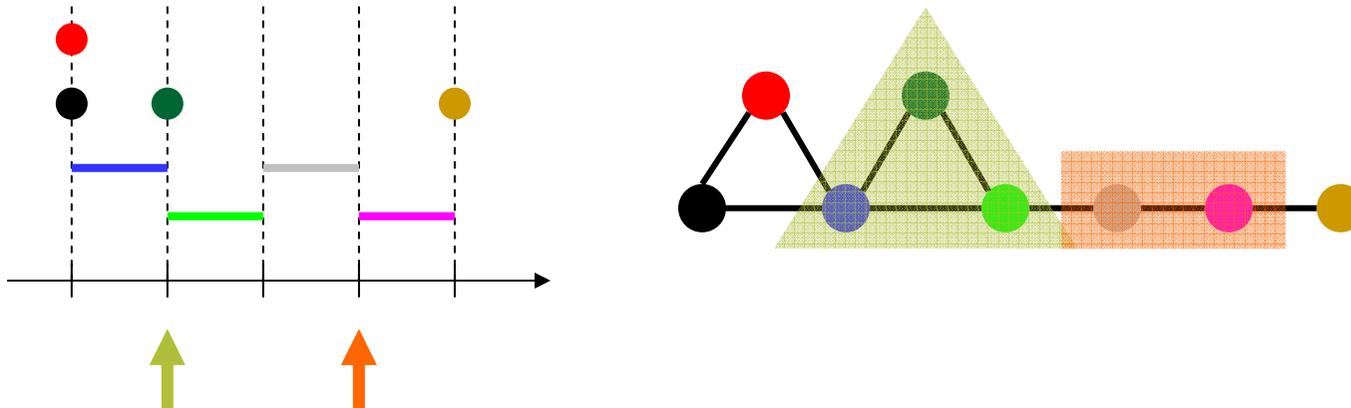
Interval Graphs

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- *Compact* interval representations of an interval graph

[Theorem 3] Let \mathcal{I} be a *compact* interval representation of a *connected* interval graph $G=(V,E)$ of n vertices with $n \geq 2$. Then $N[i]$ induces a *maximal clique* of G for each i in $[L(\mathcal{I}), R(\mathcal{I})]$. Moreover, each maximal clique M of G satisfies $M=N[i]$ for some i . That is, they make one-to-one mapping.



Interval Graphs

[Notation]

For an interval representation \mathcal{I} , we denote by $L(\mathcal{I}) := \min_{I \in \mathcal{I}} L(I)$ and by $R(\mathcal{I}) := \max_{I \in \mathcal{I}} R(I)$

- *Compact* interval representations of an interval graph

(Proof) of latter half which says a maximal clique M satisfies $M=N[i]$ for some i .

To derive a contradiction, we assume that there are **no such index i** . Let i' be the index such that $|N(i') \cap M| \geq |N(i'') \cap M|$ for any other i'' . Then there is an interval I_j such that $v_j \in M$ and $I_j \notin N[i]$. Without loss of generality, we assume that $R(I_j) < i$.

By assumption of i' , there is a vertex $v_k \in M$ such that $I_k \in N(i')$ and $I_k \notin N[R(I_j)]$ since $|N(i') \cap M| \geq |N(R(I_j)) \cap M|$ and $I_j \in N(R(I_j)) - N(i')$. Then, I_k and I_j cannot intersect, which contradicts that M contains v_k and v_j .

Interval Graphs

[Notation]

For an interval representation \mathcal{I} , we denote by $L(\mathcal{I}) := \min_{I \in \mathcal{I}} L(I)$ and by $R(\mathcal{I}) := \max_{I \in \mathcal{I}} R(I)$

- *Compact* interval representations of an interval graph

(Proof) of former half which says $N[i]$ induces a maximal clique M for each i .

It is easy to see that $N[i]$ induces a clique C . Hence we show C is maximal. To derive a contradiction, we assume that $C \subset M$ for some maximal clique M .

Then, by the latter half of the proof, there exists j such that $N[j]$ induces M . Without loss of generality, we assume $i < j$.

Then, it is not difficult to see that there are two indices i' and j' with $i \leq i' < j' \leq j$ such that $N[i'] \subset N[j']$, which contradicts that \mathcal{I} is compact. □

Interval Graphs

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For an interval representation \mathcal{I} , we denote by $L(\mathcal{I}) := \min_{I \in \mathcal{I}} L(I)$ and by $R(\mathcal{I}) := \max_{I \in \mathcal{I}} R(I)$

- *Compact* interval representations of an interval graph

[Theorem 4] Any connected interval graph $G=(V,E)$ with $|V|>1$ has at most $|V|-1$ maximal cliques.

(Proof) Immediately from Theorems 2 & 3. □

[Theorem 5] For any connected interval graph $G=(V,E)$ given in a compact interval representation form, its maximum clique can be found in $O(|V|)$ time.

(Proof) Roughly, sweep the interval representation and check $N[i]$ for each integer i . Details will be discussed in the future class with suitable data structure. □