

Cut-elimination in cyclic proof system for first-order logic

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What have we done?

- We find a counterexample to cut-elimination in CLKID^ω i.e. the cyclic proof system for first-order logic with inductive definitions
- As noted by Brotherston [Brotherston, 2006]:
 “**Conjecture 5.2.4.** *Cut is not eliminable in the system CLKID^ω . That is to say, there exists a sequent $\Gamma \vdash \Delta$ of FOL_{ID} which is provable in CLKID^ω , but is not provable without the use of the rule (Cut).*”
- We show this conjecture is correct

Cyclic proof system

- Cyclic (circular) proof system

- Each proof figure is usually a tree **with cycles**

[Brotherston, 2006, Brotherston and Simpson, 2011]

- Examples of application for software verification

- Verifying properties of concurrent processes [Schöpp and Simpson, 2002]

- Termination of pointer programs [Brotherston et al., 2008]

- Decision procedure for symbolic heaps

[Brotherston et al., 2012, Chu et al., 2015, Ta et al., 2017, Tatsuta et al., 2019]

Related works

- There exist the cut-free and complete cyclic proof systems for modal μ -calculus [Stirling, 2014, Afshari and Leigh, 2017], linear time μ -calculus [Brünnler and Lange, 2008] and Gödel-Löb provability logic [Shamkanov, 2014]
- Kimura et al. [KIMURA et al., 2020] show that the cut-elimination property in the cyclic proof system for separation logic does not hold

Inductive predicate 1

Inductive predicate: a formalisation of the inductive definition with productions

Definition 1 (Inductive definition set)

A **production** is defined as

$$\frac{Q_1 \mathbf{u}_1 \quad \cdots \quad Q_h \mathbf{u}_h \quad P_{j_1} \mathbf{t}_1 \quad \cdots \quad P_{j_m} \mathbf{t}_m}{P_i \mathbf{t}} ,$$

where each of $Q_1 \mathbf{u}_1, \dots, Q_h \mathbf{u}_h$ denotes an atomic formula with an ordinal predicate symbol and each of $P_{j_1} \mathbf{t}_1, \dots, P_{j_m} \mathbf{t}_m$ and $P_i \mathbf{t}$ denotes an atomic formula with an inductive predicate symbol.

Inductive predicate 2

Examples:

Natural Number $N(x)$

$$\frac{}{N(0)} \quad \frac{N(x)}{N(sx)}$$

Addition $Add_1(x, y, z)$

$$\frac{}{Add_1(0, y, y)} \quad \frac{x + y = z \quad Add_1(x, y, z)}{Add_1(sx, y, sz)}$$

Inductive predicate 3

Note

- An **inductive definition set** is a finite set of productions.
- The semantics of inductive predicates is obtained by considering the least fixed point of a monotone operator constructed from the inductive definition set [Brotherston and Simpson, 2011].

Inference rules of CLKID^ω

Each red formula is the principal formula of each rule

$$\begin{array}{c}
 \Gamma \cap \Delta = \emptyset \quad \frac{}{\Gamma \vdash \Delta} \text{ (Axiom)} \quad \Gamma' \subset \Gamma, \Delta' \subset \Delta \quad \frac{\Gamma' \vdash \Delta'}{\Gamma \vdash \Delta} \text{ (Weak)} \quad \frac{\Gamma \vdash F, \Delta \quad \Gamma, F \vdash \Delta}{\Gamma \vdash \Delta} \text{ (Cut)} \quad \frac{\Gamma \vdash \Delta}{\Gamma[\theta] \vdash \Delta[\theta]} \text{ (Subst)} \\
 \\
 \frac{\Gamma \vdash F, \Delta}{\Gamma, \neg F \vdash \Delta} (\neg \text{ L}) \quad \frac{\Gamma, F \vdash \Delta}{\Gamma \vdash \neg F, \Delta} (\neg \text{ R}) \quad \frac{\Gamma, F \vdash \Delta \quad \Gamma, G \vdash \Delta}{\Gamma, F \vee G \vdash \Delta} (\vee \text{ L}) \quad \frac{\Gamma \vdash F, G, \Delta}{\Gamma \vdash F \vee G, \Delta} (\vee \text{ R}) \\
 \\
 \frac{\Gamma, F, G \vdash \Delta}{\Gamma, F \wedge G \vdash \Delta} (\wedge \text{ L}) \quad \frac{\Gamma \vdash F, \Delta \quad \Gamma \vdash G, \Delta}{\Gamma \vdash F \wedge G, \Delta} (\wedge \text{ R}) \quad \frac{\Gamma \vdash F, \Delta \quad \Gamma, G \vdash \Delta}{\Gamma, F \rightarrow G \vdash \Delta} (\rightarrow \text{ L}) \quad \frac{\Gamma, F \vdash G, \Delta}{\Gamma \vdash F \rightarrow G, \Delta} (\rightarrow \text{ R}) \\
 \\
 \frac{\Gamma, F[x := t] \vdash \Delta}{\Gamma, \forall x F \vdash \Delta} (\forall \text{ L}) \quad x \notin \text{FV}(\Gamma \cup \Delta) \quad \frac{\Gamma \vdash F, \Delta}{\Gamma \vdash \forall x F, \Delta} (\forall \text{ R}) \quad x \notin \text{FV}(\Gamma \cup \Delta) \quad \frac{\Gamma, F \vdash \Delta}{\Gamma, \exists x F \vdash \Delta} (\exists \text{ L}) \quad \frac{\Gamma \vdash F[x := t], \Delta}{\Gamma \vdash \exists x F, \Delta} (\exists \text{ R}) \\
 \\
 \frac{\Gamma[x := u, y := t] \vdash \Delta[x := u, y := t]}{\Gamma[x := t, y := u], t = u \vdash \Delta[x := t, y := u]} (= \text{ L}) \quad \frac{}{\Gamma \vdash t = t, \Delta} (= \text{ R})
 \end{array}$$

The inference rules for inductive predicates 1

For each production

$$\frac{Q_1 \mathbf{u}_1(\mathbf{x}) \quad \dots \quad Q_h \mathbf{u}_h(\mathbf{x}) \quad P_{j_1} \mathbf{t}_1(\mathbf{x}) \quad \dots \quad P_{j_m} \mathbf{t}_m(\mathbf{x})}{P_i \mathbf{t}(\mathbf{x})} ,$$

there is a corresponding inference rule

$$\frac{\Gamma \vdash Q_1 \mathbf{u}_1(\mathbf{u}), \Delta \quad \dots \quad \Gamma \vdash Q_h \mathbf{u}_h(\mathbf{u}), \Delta \quad \Gamma \vdash P_{j_1} \mathbf{t}_1(\mathbf{u}), \Delta \quad \dots \quad \Gamma \vdash P_{j_m} \mathbf{t}_m(\mathbf{u}), \Delta}{\Gamma \vdash P_i \mathbf{t}(\mathbf{u}), \Delta} (P_i R_r) .$$

The inference rules for inductive predicates 2

The left introduction rule for inductive predicates is

$$\frac{\text{case distinctions}}{\Gamma, P_i \mathbf{u} \vdash \Delta} \text{ (Case } P_i \text{) ,}$$

where for each production having the predicate P_i in its conclusion

$$\frac{Q_1 \mathbf{u}_1(\mathbf{x}) \quad \dots \quad Q_h \mathbf{u}_h(\mathbf{x}) \quad P_{j_1} \mathbf{t}_1(\mathbf{x}) \quad \dots \quad P_{j_m} \mathbf{t}_m(\mathbf{x})}{P_i \mathbf{t}(\mathbf{x})} ,$$

there is a corresponding case distinction

$$\Gamma, \mathbf{u} = \mathbf{t}(\mathbf{y}), Q_1 \mathbf{u}_1(\mathbf{y}), \dots, Q_h \mathbf{u}_h(\mathbf{y}), P_{j_1} \mathbf{t}_1(\mathbf{y}), \dots, P_{j_m} \mathbf{t}_m(\mathbf{y}) \vdash \Delta,$$

where \mathbf{y} is a sequence of distinct fresh variables of the same length as \mathbf{x} .

The inference rules for Add_1

$$\frac{}{\text{Add}_1(0, y, y)}$$

$$\frac{\text{Add}_1(x, y, z)}{\text{Add}_1(sx, y, sz)}$$

$$\frac{}{\Gamma \vdash \Delta, \text{Add}_1(0, b, b)} \text{ (Add}_1 \text{ R}_1)$$

$$\frac{\Gamma \vdash \Delta, \text{Add}_1(a, b, c)}{\Gamma \vdash \Delta, \text{Add}_1(sa, b, sc)} \text{ (Add}_1 \text{ R}_2)$$

$$\frac{\Gamma, a = 0, b = y, c = y \vdash \Delta \quad \Gamma, a = sx, b = y, c = sz, \text{Add}_1(x, y, z) \vdash \Delta}{\Gamma, \text{Add}_1(a, b, c) \vdash \Delta} \text{ (Case Add}_1) ,$$

where x, y, z are fresh

The inference rules for inductive predicates 3

Note

Case-descendants of the principal formula $P_i \mathbf{u}$ in a (Case P_i) are the formulas

$P_{j_1} \mathbf{t}_1(\mathbf{y}), \dots, P_{j_m} \mathbf{t}_m(\mathbf{y})$.

Trace 1

T : a derivation figure

$(\Gamma_i \vdash \Delta_i)_{0 \leq i < \alpha}$: a path in T

Define a **trace following** $(\Gamma_i \vdash \Delta_i)_{0 \leq i < \alpha}$ to be a sequence of formulas $(\tau_i)_{0 \leq i < \alpha}$ such that the following hold:

- 1 Each τ_i is an element of Γ_i and an atomic formula with an inductive predicate.
- 2 If $\Gamma_i \vdash \Delta_i$ is the conclusion of (Subst), then $\tau_i \equiv \tau_{i+1}[\theta]$, where θ is the substitution associated with the rule instance.

Trace 2

- ③ If $\Gamma_i \vdash \Delta_i$ is the conclusion of ($=$ L) with the principal formula $t = u$, then there are a formula F and variables x, y such that $\tau_i \equiv F[x := t, y := u]$ and $\tau_{i+1} \equiv F[x := u, y := t]$.
- ④ If $\Gamma_i \vdash \Delta_i$ is the conclusion of (Case P_i), then either
 - τ_i is the principal formula of the rule instance and τ_{i+1} is a case-descendant of τ_i or
 - τ_{i+1} is the same as τ_i .

In the former case, i is said to be a **progress point** of the trace.

Trace 3

- 5 If $\Gamma_i \vdash \Delta_i$ is the conclusion of any other rules, then $\tau_{i+1} \equiv \tau_i$.

Note

Call a trace having infinitely many progress points an **infinitely progressing trace**.

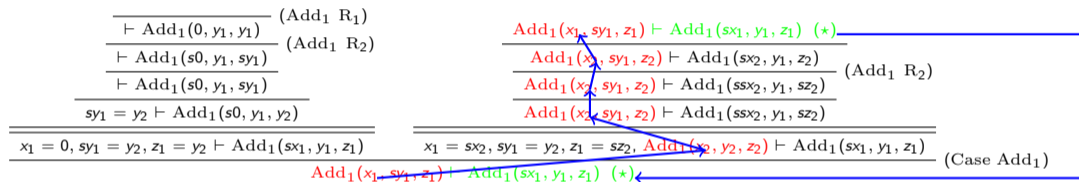
Global trace condition

Definition 2 (Global trace condition)

If, for every infinite path $(v_i)_{i \geq 0}$ in a derivation figure, there exists an infinitely progressing trace following a tail of the path $(v_i)_{i \geq k}$ with $k \geq 0$, then we say the derivation figure satisfies the **global trace condition**.

A CLKID^ω proof is a derivation tree with cycles satisfying the global trace condition.

Examples of CLKID^ω proof



Red formulas denote an infinitely many progressing trace

Green sequents denote a bud and the corresponding companion

The blue line denotes an infinite path

The inference rules for Add_2

$\text{Add}_2(x, y, z) : x + y = z$

$$\frac{}{\text{Add}_2(0, y, y)}$$

$$\frac{\text{Add}_2(x, sy, z)}{\text{Add}_2(sx, y, z)}$$

$$\frac{}{\vdash \text{Add}_2(0, b, b)} \text{ (Add}_2 \text{ R}_1)$$

$$\frac{\Gamma \vdash \Delta, \text{Add}_2(a, sb, c)}{\Gamma \vdash \Delta, \text{Add}_2(sa, b, c)} \text{ (Add}_2 \text{ R}_2)$$

$$\frac{\Gamma, a = 0, b = y, c = y \vdash \Delta \quad \Gamma, a = sx, b = y, c = z, \text{Add}_2(x, sy, z) \vdash \Delta}{\Gamma, \text{Add}_2(a, b, c) \vdash \Delta} \text{ (Case Add}_2)$$

where x, y, z are fresh

Main theorem

Theorem 3 (Main theorem)

- 1 $\text{Add}_2(x, y, z) \vdash \text{Add}_1(x, y, z)$ is provable in CLKID^ω .
- 2 $\text{Add}_2(x, y, z) \vdash \text{Add}_1(x, y, z)$ is not cut-free provable in CLKID^ω .

CLKID^ω proof of $\text{Add}_2(x, y, z) \vdash \text{Add}_1(x, y, z)$

\mathcal{D}_1

$$\begin{array}{c}
 \frac{}{\vdash \text{Add}_1(0, y_1, y_1)} \text{ (Add}_1 \text{ R}_1) \\
 \frac{}{\vdash \text{Add}_1(s0, y_1, sy_1)} \text{ (Add}_1 \text{ R}_2) \\
 \hline
 \vdash \text{Add}_1(s0, y_1, sy_1) \\
 \hline
 sy_1 = y_2 \vdash \text{Add}_1(s0, y_1, y_2) \\
 \hline
 x_1 = 0, sy_1 = y_2, z_1 = y_2 \vdash \text{Add}_1(sx_1, y_1, z_1)
 \end{array}
 \qquad
 \begin{array}{c}
 \text{Add}_1(x_1, sy_1, z_1) \vdash \text{Add}_1(sx_1, y_1, z_1) \text{ (*)} \\
 \hline
 \text{Add}_1(x_2, sy_1, z_2) \vdash \text{Add}_1(sx_2, y_1, z_2) \\
 \hline
 \text{Add}_1(x_2, sy_1, z_2) \vdash \text{Add}_1(ssx_2, y_1, sz_2) \text{ (Add}_1 \text{ R}_2) \\
 \hline
 \text{Add}_1(x_2, sy_1, z_2) \vdash \text{Add}_1(ssx_2, y_1, sz_2) \\
 \hline
 x_1 = sx_2, sy_1 = y_2, z_1 = sz_2, \text{Add}_1(x_2, y_2, z_2) \vdash \text{Add}_1(sx_1, y_1, z_1) \text{ (Case Add}_1) \\
 \hline
 \text{Add}_1(x_1, sy_1, z_1) \vdash \text{Add}_1(sx_1, y_1, z_1) \text{ (*)}
 \end{array}$$

\mathcal{D}_2

$$\begin{array}{c}
 \frac{}{\vdash \text{Add}_1(0, y_1, y_1)} \text{ (Add}_1 \text{ R}_1) \\
 \hline
 x = 0, y = y_1, z = y_1 \vdash \text{Add}_1(x, y, z)
 \end{array}
 \qquad
 \begin{array}{c}
 \text{Add}_2(x, y, z) \vdash \text{Add}_1(x, y, z) \text{ (†)} \\
 \hline
 \text{Add}_2(x_1, sy_1, z_1) \vdash \text{Add}_1(x_1, sy_1, z_1) \\
 \hline
 \text{Add}_2(x_1, sy_1, z_1) \vdash \text{Add}_1(sx_1, y_1, z_1) \\
 \hline
 x = sx_1, y = y_1, z = z_1, \text{Add}_2(x_1, sy_1, z_1) \vdash \text{Add}_1(x, y, z) \text{ (Case Add}_2) \\
 \hline
 \text{Add}_2(x, y, z) \vdash \text{Add}_1(x, y, z) \text{ (†)}
 \end{array}$$

Proof sketch of the main theorem 1

- Assume there exists a cut-free CLKID^ω proof \mathcal{P} of $\text{Add}_2(x, y, z) \vdash \text{Add}_1(x, y, z)$

Definition 4 (\cong_Γ)

Γ : a set of formulas in which all terms occurring are of the form $s^n x$ or $s^n 0$.

Define the relation \cong_Γ to be the smallest congruence relation on terms which satisfies that $t_1 = t_2 \in \Gamma$ implies $t_1 \cong_\Gamma t_2$.

Proof sketch of the main theorem 2

Definition 5 (Index)

$\Gamma \vdash \Delta$: a sequent Fix $\text{Add}_2(a, b, c) \in \Gamma$.

Define **the index of $\text{Add}_2(a, b, c)$ in $\Gamma \vdash \Delta$** as follows:

- 1 If $s^n b \cong_{\Gamma} s^m b'$ for any $n, m \in \mathbb{N}$, $\text{Add}_1(a', b', c') \in \Delta$, then the index is \perp .
- 2 If $\exists n, \exists m \in \mathbb{N}$ s.t. $s^n b \cong_{\Gamma} s^m b'$ for some $\text{Add}_1(a', b', c') \in \Delta$ and $m - n$ is unique (namely $s^{n'} b \cong_{\Gamma} s^{m'} b'$ implies $m - n = m' - n'$ for any $\text{Add}_1(a', b', c') \in \Delta$), then the index is $m - n$.

Proof sketch of the main theorem 3

Definition 6 (Index sequent)

The sequent $\Gamma \vdash \Delta$ is said to be an **index sequent** if the following conditions hold:

- 1 If $t \in B_1(\Gamma \vdash \Delta)$ and $u \in C(\Gamma \vdash \Delta)$, then $s^n t \not\cong_{\Gamma} s^m u$ for any $n, m \in \mathbb{N}$.
- 2 If $s^n b \cong_{\Gamma} s^m b'$ with $b, b' \in B_1(\Gamma \vdash \Delta)$, then $n = m$.

$$B_1(\Gamma \vdash \Delta) = \{b \mid \text{Add}_1(a, b, c) \in \Delta\},$$

$$C(\Gamma \vdash \Delta) = \{c \mid \text{Add}_2(a, b, c) \in \Gamma \text{ or } \text{Add}_1(a, b, c) \in \Delta\}.$$

Proof sketch of the main theorem 4

Lemma 7

The index of each $\text{Add}_2(a, b, c)$ in an index sequent is defined.

Proof sketch of the main theorem 5

A **switching point** is a node where the corresponding rule is (Case Add₂) whose principal formula's index is \perp .

$$\begin{array}{c}
 \vdots \\
 \vdots \\
 \vdots \\
 \vdots \\
 \vdots \\
 \vdots \\
 \vdots \\
 \vdots \\
 \vdots \\
 \vdots \\
 \vdots \\
 \vdots
 \end{array}
 \frac{
 \frac{
 \frac{
 (\heartsuit) \text{Add}_2(x_1, sy_1, z_1)[\perp], \text{Add}_2(x, y, z)[0] \vdash \text{Add}_1(x, y, z)
 }{
 \text{Add}_2(x_2, sy_2, z_2)[\perp], \text{Add}_2(x, y, z)[0] \vdash \text{Add}_1(x, y, z)
 }
 }{
 x_1 = sx_2, sy_1 = y_2, z_1 = z_2, \text{Add}_2(x_2, sy_2, z_2)[\perp], \text{Add}_2(x, y, z)[0] \vdash \text{Add}_1(x, y, z)
 }
 \text{(Switching)}
 }{
 \frac{
 (\heartsuit) \text{Add}_2(x_1, sy_1, z_1)[\perp], \text{Add}_2(x, y, z)[0] \vdash \text{Add}_1(x, y, z)
 }{
 x = sx_1, y = y_1, z = z_1, \text{Add}_2(x_1, sy_1, z_1)[1], \text{Add}_2(x, y, z)[0] \vdash \text{Add}_1(x, y, z)
 }
 \text{(Case Add}_2\text{)}
 }{
 \text{Add}_2(x, y, z)[0] \vdash \text{Add}_1(x, y, z)
 }$$

Proof sketch of the main theorem 6

Definition 8 (Index path)

A path $(v_i)_{0 \leq i < \alpha}$ is said to be an **index path** if the following conditions hold:

- 1 $\text{Seq}(v_0)$ is an index sequent
- 2 If v_i is the left assumption of (Case Add₂) for $i > 0$, v_{i-1} is a switching point

Note

The rightmost path from an index path is an index path.

Proof sketch of the main theorem 7

Lemma 9

Every sequent in an index path is an index sequent.

Lemma 10

Let $(v_i)_{i \geq 0}$ be an infinite index path.

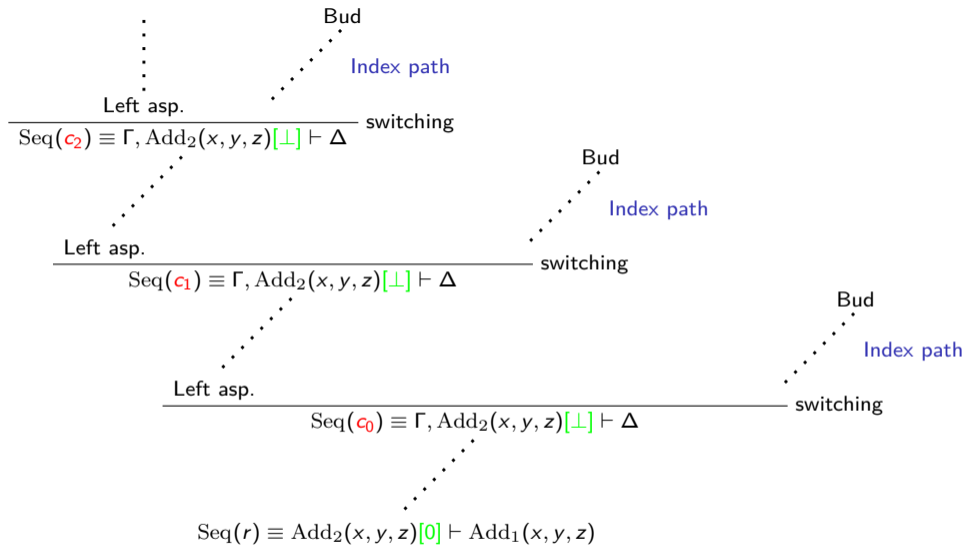
There exists $l \in \mathbb{N}$ such that the following conditions satisfy:

- 1 Rule(v_l) is a switching point
- 2 v_{l+1} is the right assumption of (Case Add₂)

Proof sketch of the main theorem 8

Show that there exists a sequence $(c_i)_{i \in \mathbb{N}}$ of nodes in \mathcal{P} which satisfies the following conditions:

- 1 c_i is a switching point.
- 2 For a node v on the path from the root to c_n with $\text{Rule}(v) = (\text{Case Add}_2)$ for each $n \in \mathbb{N}$, v is a switching point if and only if the child of v on the path from the root to c_n is the left assumption of v .
- 3 For all $i, j \in \mathbb{N}$ with $j > i$, the height of c_j is greater than the height of c_i .



By repeating this process, we get a set of infinite nodes $\{c_i | i \in \mathbb{N}\}$. **CONTRADICTION!!**

Conclusion

Main result

There exists a sequent, not cut-free provable in CLKID^ω but provable in CLKID^ω .

In other words, (Cut) cannot be eliminated in CLKID^ω .

Future work

Can we restrict principal formulas of (Cut) without changing provability?

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